



MULTIMODE GNSS RECEIVER

Use of a table / almanac that allows to frame the uncertainty on a GPS measurement

Technological benefits

Comprehensive analysis of error items

- Taking into account all the error items
- Contributions quantification of each item to the overall error

A controlled error

- Errors grouping of each station in order to frame the maximum error

Invention overview

The aim of this invention is to frame the error on the GPS measurements in order to have a reliable range of this error and to improve the system integrity. This objective is achieved by identifying and quantifying the error positions. These errors are then combined to determine the overall error.

Potential applications

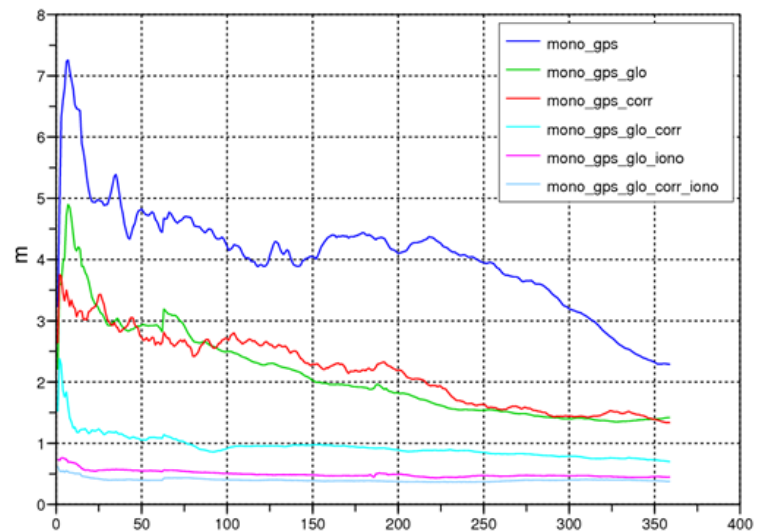
GPS location

- GPS positioning errors reduction

Autonomous vehicles

- Reduction of accidents due to GPS positioning errors thanks to better framing of these errors

Mono-frequency convergence



Commercial benefits

Control of accident risks

- Accidents are more predictable and more controlled

Accident reduction

- It is thus possible to reduce accidents due to positioning errors (in particular on autonomous vehicles)

TRL : 5-6

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